

# Sensing, Computing, Actuating

## Lecture 15 - Exam training

**Disclaimer:** This document contains that exercises that cover part of the material that you need to study in preparation of the exam. The exam will also cover material not discussed in these exercises. Furthermore, the exam will contain more exercises.

### Exercise 1: Electronic Stability Program

ESP assists a driver to keep a vehicle on the road during dangerous driving conditions. For this purpose, the ESP system uses a large number of sensors in the vehicle. One of these sensors measures the angle of the steering-wheel and steering-column and the speed with which the driver changes this angle (note that one sensor measures both quantities). The RVDT (rotary variable differential transducer) from Figure 1 can be used to measure the angle (and its rate of change). When the driver moves the steer from the central position ( $\Theta = 0^\circ$ ) to the left or to the right, then this will lead to a change in the output voltage of the sensor. This electrical signal can then be send to the ESP computer. The primary winding of this RVDT is connected to a voltage supply that produces a sinusoidal voltage with an amplitude of 5V with a frequency of 10 Hz. The RVDT has a sensitivity  $S$  of  $100 \mu\text{V}/(^\circ/\text{V})$ . The output voltage of the RVDT is equal to:

$$v_2 - v_1 = S \cdot \Theta \cdot v_r$$

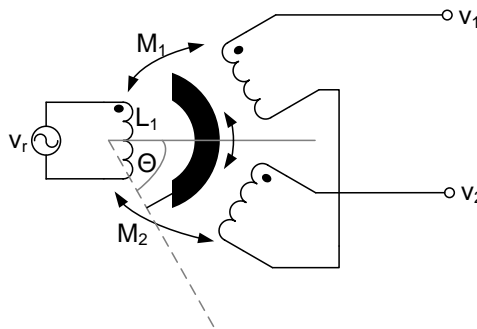


Figure 1: Measuring an angle using an RVDT.

- (a) A driver moves the steer in 1 second from an angle  $\Theta = -30^\circ$  to an angle  $\Theta = +30^\circ$ . Draw the amplitude of the output voltage  $v_2 - v_1$  as a function of the angle  $\Theta$ . (Clearly show the dimensions on both axis.)
- (b) The signal coming from the RVDT is too weak to be directly send to the ESP computer. The signal should first be amplified. For this purpose, the sensor from Figure 1 is connected to an instrumentation amplifier. The resulting circuit is shown in Figure 2. The instrumentation amplifier uses three operational amplifiers. You may assume that these op-amps show an ideal behaviour. Show that the output voltage  $v_o$  of the instrumentation amplifier in Figure 2 is equal to:

$$v_o = \left(1 + \frac{2R_2}{R_1}\right) \frac{R_4}{R_3} v_d$$

with  $v_d = v_2 - v_1$ .

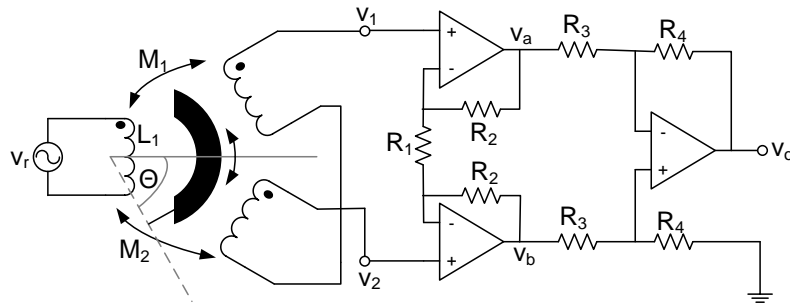


Figure 2: RVDT with instrumentation amplifier.

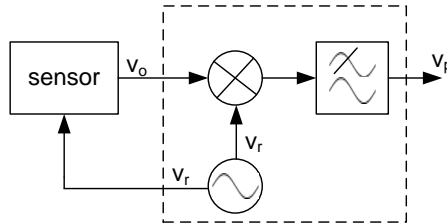


Figure 3: Sensor with phase sensitive detector.

- (c) Assume that the resistors  $R_3$  and  $R_4$  in the instrumentation amplifier from Figure 2 both have a resistance of  $100 \text{ k}\Omega$ . What ratio should the resistors  $R_1$  and  $R_2$  have such that the amplitude of the output voltage  $v_o$  is equal to  $0 \text{ V}$  when  $\Theta = 0^\circ$  and  $5 \text{ V}$  (peak) when  $\Theta = 30^\circ$ ?
- (d) The rotation sensor from Figure 2 is connected to a phase sensitive detector. This detector consists of an analogue multiplier connected to a low-pass filter. Using this processing circuit, it is possible to recover the magnitude and direction of the rotation from the output signal of the sensor. The block diagram of a phase sensitive detector is shown in Figure 3. The angle of the steering-wheel is given as a function  $\Theta(t)$ . Assume further that the reference voltage  $v_r$  is equal to:

$$v_r(t) = V_r \cdot \cos(\omega_r \cdot t)$$

The output voltage of the sensor,  $v_o$ , is then equal to:

$$v_o(t) = S \cdot \Theta(t) \cdot v_r(t)$$

Show that the output voltage of the phase sensitive detector,  $v_p$ , is equal to:

$$v_p(t) = S \cdot \Theta(t) \cdot \frac{V_r^2}{2}$$

*Hint:*  $\cos(A)\cos(B) = \frac{1}{2} (\cos(A + B) + \cos(A - B))$ .

- (e) In stead of a phase sensitive detector, it is also possible to connect the output signal of the RCDT to a double-sided rectifier with a low-pass filter as is shown in Figure 4. Is it possible to reconstruct from the output signal ( $v_{o2} - v_{o1}$ ) the direction (positive or negative angle)? (Explain your answer.)

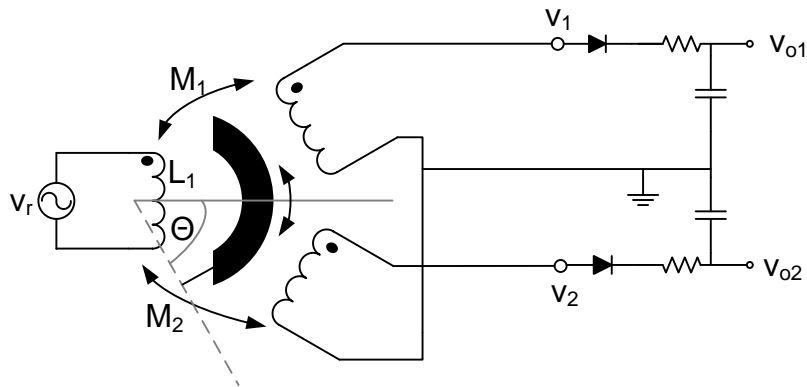


Figure 4: Double-sided rectifier with low-pass filter.

- (f) An RVDT measures the rotation of an object through the change in coupling between a primary and two secondary coils. Another way to measure a rotation would be to use a Hall effect sensor. Explain the operation of a Hall effect sensor. Clearly indicate how you can use the sensor to measure a rotation.

**Exercise 2: exhaust gas temperature measurement**

It is necessary to change the ratio between fuel and air in a combustion engine to maximize the efficiency of the engine. The objective is to keep the temperature of the gasses going through the exhaust pipe within a certain temperature range. Because of the high temperature of these gases, it is necessary to use a thermocouple to measure this temperature. A thermocouple can only measure a temperature difference. Therefore it is necessary to also add a reference sensor to the circuit. This sensor is then used to measure the absolute temperature at the reference junction.

The thermocouple in Figure 5 contains a reference junction compensation based on a RTD temperature sensor. The output voltage of this sensor ( $v_{ref}$ ) is given by the following transfer function:  $v_{ref} = 10mV/^{\circ}C \cdot T_a$  with  $T_a$  the environmental temperature at the reference junction. The output of the reference temperature sensor is connected to the reference input of the instrumentation amplifier. It holds for this instrumentation amplifier:

$$v_o - v_{ref} = \left(1 + \frac{2R_2}{R_1}\right) \frac{R_4}{R_3} (v_2 - v_1) = (1 + G) k (v_2 - v_1)$$

The ratio of the resistors in the instrumentation amplifier is equal to:  $k = R_4/R_3 = 1$ . The thermocouple itself is a J-type (Cn/Fe) thermocouple with a sensitivity  $S_J = 54\mu V/K$ .

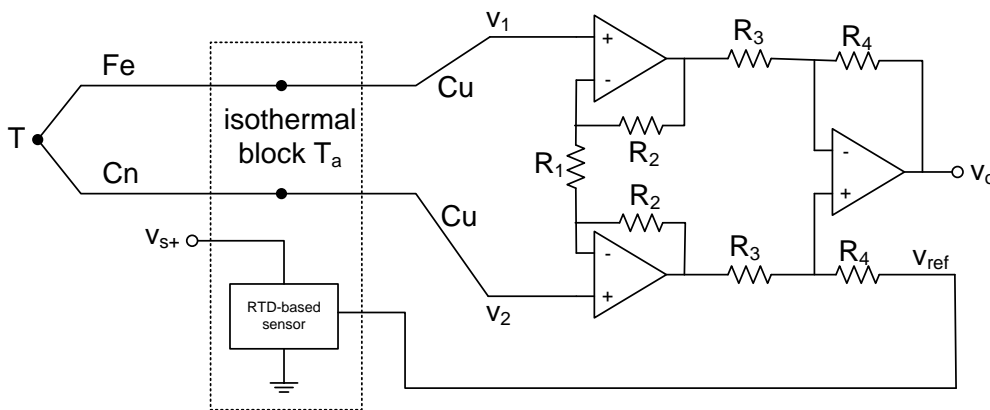


Figure 5: Compensation with a RTD-based sensor and instrumentation amplifier.

- (a) There are three important laws that you can use when analysing thermocouples, namely the law of the homogeneous circuits, the law of intermediate metals, and the law of intermediate temperatures. Show using these laws that the voltage across the thermocouple shown in Figure 5 is equal to:

$$v_2 - v_1 = V_T - V_{T_a} = S_J \cdot (T - T_a)$$

*Hint:* The Seebeck coefficient  $\alpha_{Cn/Fe}$  of a J-type thermocouple is equal to:  $\alpha_{Cn/Fe} = S_J$ .

- (b) What gain,  $G$ , should the instrumentation amplifier have to get an output voltage  $v_o$  that is independent of the environmental temperature?
- (c) A thermocouple uses three thermo-electrical effects. Name at least two of these effects and explain briefly (maximally 200 words) how these effects work.
- (d) Instead of a thermocouple you can also use a thermistor to measure the temperature. The operation of a thermistor is based on the thermoresistive effect. Explain how this effect works in an NTC thermistor.
- (e) Give at least three reasons why we prefer a transducer who produces a signal in the electrical domain over a transducer who produces a signal in any of the other signal domains.
- (f) Give a definition (maximally 100 words) for the following terms:
- Transducer
  - Sensor
  - Sensitivity of a sensor
  - Transfer function of a sensor